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ON SOME PERTURBATIONS OF A STABLE PROCESS AND SOLUTIONS OF THE CAUCHY PROBLEM FOR A CLASS OF PSEUDO-DIFFERENTIAL EQUATIONS

A fundamental solution of some class of pseudo-differential equations is constructed by a method based on the theory of perturbations. We consider a symmetric α -stable process in multidimensional Euclidean space. Its generator \mathbf{A} is a pseudo-differential operator whose symbol is given by $-c|\lambda|^\alpha$, where the constants $\alpha \in (1, 2)$ and $c > 0$ are fixed. The vector-valued operator \mathbf{B} has the symbol $2ic|\lambda|^{\alpha-2}\lambda$. We construct a fundamental solution of the equation $u_t = (\mathbf{A} + (a(\cdot), \mathbf{B}))u$ with a continuous bounded vector-valued function a .

Key words and phrases: stable process, Cauchy problem, pseudo-differential equation, transition probability density.

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INTRODUCTION

Let \mathbf{A} denote a pseudo-differential operator that acts on a twice continuously differentiable bounded function $(\varphi(x))_{x \in \mathbb{R}^d}$ according to the following rule

$$(\mathbf{A}\varphi)(x) = \frac{c}{\varkappa} \int_{\mathbb{R}^d} \frac{\varphi(x+y) - \varphi(x) - (y, \nabla\varphi(x))}{|y|^{d+\alpha}} dy, \quad (1)$$

where $c > 0$, $1 < \alpha < 2$, $d \in \mathbb{N}$ are some constants, $\varkappa = -\frac{2\pi^{\frac{d-1}{2}}\Gamma(2-\alpha)\Gamma\left(\frac{\alpha+1}{2}\right)\cos\frac{\pi\alpha}{2}}{\alpha(\alpha-1)\Gamma\left(\frac{d+\alpha}{2}\right)}$ and

∇ is the Hamilton operator (gradient). Here (\cdot, \cdot) denotes the scalar product in \mathbb{R}^d .

It is known that the function $u(t, x) = \int_{\mathbb{R}^d} \varphi(y)g(t, x, y) dy$, where

$$g(t, x, y) = \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} e^{i(y-x, \lambda) - ct|\lambda|^\alpha} d\lambda, \quad (2)$$

is a solution of the following Cauchy problem

$$\begin{aligned} \frac{\partial u(t, x)}{\partial t} &= \mathbf{A}_x u(t, x), \quad t > 0, x \in \mathbb{R}^d, \\ u(0+, x) &= \varphi(x), \quad x \in \mathbb{R}^d, \end{aligned} \quad (3)$$

for any bounded continuous function $(\varphi(x))_{x \in \mathbb{R}^d}$.

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If an operator acts on a function of several arguments, then it will be provided by a corresponding subscript, for example, \mathbf{A}_x in (3) means that the operator \mathbf{A} is acting on $u(t, x)$ as the function of the variable x .

Note, that the function $(g(t, x, y))_{t>0, x \in \mathbb{R}^d, y \in \mathbb{R}^d}$ serves as transition probability density of a Markov process in \mathbb{R}^d , called a symmetric stable process. The operator \mathbf{A} is the generator of it.

Let us consider the equation

$$\frac{\partial u(t, x)}{\partial t} = \mathbf{A}_x u(t, x) + (a(x), \mathbf{B}_x u(t, x)), \quad t > 0, x \in \mathbb{R}^d, \quad (4)$$

with some \mathbb{R}^d -valued function $(a(x))_{x \in \mathbb{R}^d}$ and d -dimensional pseudo-differential operator \mathbf{B} of the order less than α .

In this article, we consider the case, where the a is a bounded continuous function and the operator \mathbf{B} is defined on a differentiable bounded function $(\varphi(x))_{x \in \mathbb{R}^d}$ by the equality

$$(\mathbf{B}\varphi)(x) = \frac{2c}{\alpha \pi} \int_{\mathbb{R}^d} \frac{\varphi(x+y) - \varphi(x)}{|y|^{d+\alpha}} y dy.$$

Note, that $\mathbf{A} = \frac{1}{2} \mathbf{div}(\mathbf{B})$.

We construct a fundamental solution of equation (4) by perturbing the transition probability density of a symmetric stable process. The fundamental solution of equation (4) was constructing in [2] under the assumption that the function a satisfied Holder's condition.

Symmetric stable processes were perturbed by terms of the type $(a(x), \nabla)$ under various assumptions on the function $(a(x))_{x \in \mathbb{R}^d}$ in many papers (see, for example, [1, 3, 5, 6]). The perturbation of stable processes with delta-function in coefficient is constructed in [4].

1 PERTURBATION OF A STABLE PROCESS

We consider a function $(G(t, x, y))_{t>0, x \in \mathbb{R}^d, y \in \mathbb{R}^d}$ as a result of perturbing the transition probability density $g(t, x, y)$ of a symmetric stable process, if it is a solution of the following equation

$$G(t, x, y) = g(t, x, y) + \int_0^t d\tau \int_{\mathbb{R}^d} g(t-\tau, x, z) (\mathbf{B}_z G(\tau, z, y), a(z)) dz. \quad (5)$$

Now we define a function $(e(x))_{x \in \mathbb{R}^d}$ by the equality $e(x) = \frac{1}{|a(x)|} a(x)$ for $x \in \mathbb{R}^d$ such that $|a(x)| \neq 0$ and an arbitrary value (with preservation of the measurability) otherwise. Then the equation (5) takes the form

$$G(t, x, y) = g(t, x, y) + \int_0^t d\tau \int_{\mathbb{R}^d} g(t-\tau, x, z) (\mathbf{B}_z G(\tau, z, y), e(z)) |a(z)| dz. \quad (6)$$

It is easy to establish the following equality using the representation (2) and integration by parts $\mathbf{B}_x g(t, x, y) = \frac{2}{\alpha} \frac{y-x}{t} g(t, x, y)$. Denote by $V_0(t, x, y)$ a function that is given by the equality

$$V_0(t, x, y) = (\mathbf{B}_x g(t, x, y), e(x)) = \frac{2}{\alpha} \frac{(y-x, e(x))}{t} g(t, x, y). \quad (7)$$

We will construct the solution of (6) in the form

$$G(t, x, y) = g(t, x, y) + \int_0^t d\tau \int_{\mathbb{R}^d} g(t-\tau, x, z) V(\tau, z, y) |a(z)| dz, \quad (8)$$

where the function $V(t, x, y)$ satisfies the equation

$$V(t, x, y) = V_0(t, x, y) + \int_0^t d\tau \int_{\mathbb{R}^d} V_0(t - \tau, x, z) V(\tau, z, y) |a(z)| dz. \quad (9)$$

The equation (9) can be solved by the method of successive approximations, namely its solution will be found in the form

$$V(t, x, y) = \sum_{k=0}^{\infty} V_k(t, x, y), \quad (10)$$

where $V_0(t, x, y)$ is defined by the equality (7) and for $k \geq 1$ the following equality

$$V_k(t, x, y) = \int_0^t d\tau \int_{\mathbb{R}^d} V_0(t - \tau, x, z) V_{k-1}(\tau, z, y) |a(z)| dz$$

is valid.

The well-known estimate (see [2]) ($t > 0$, $x \in \mathbb{R}^d$, $y \in \mathbb{R}^d$, and $N > 0$ is a constant)

$$g(t, x, y) \leq N \frac{t}{(t^{1/\alpha} + |y - x|)^{d+\alpha}} \quad (11)$$

allows us to write down

$$|V_0(t, x, y)| \leq \frac{2}{\alpha} N \frac{|y - x|}{(t^{1/\alpha} + |y - x|)^{d+\alpha}} \leq \frac{2}{\alpha} \frac{N}{(t^{1/\alpha} + |y - x|)^{d+\alpha-1}}.$$

Then, we get that the inequality

$$|V_k(t, x, y)| \leq \|a\| \frac{2N}{\alpha} \int_0^t d\tau \int_{\mathbb{R}^d} \frac{1}{((t - \tau)^{1/\alpha} + |z - x|)^{d+\alpha-1}} |V_{k-1}(\tau, z, y)| dz$$

is true, where $\|a\| = \sup_{x \in \mathbb{R}^d} |a(x)|$.

In order to estimate V_k we make use of the following inequality (see [2])

$$\begin{aligned} & \int_0^t d\tau \int_{\mathbb{R}^d} \frac{1}{((t - \tau)^{1/\alpha} + |z - x|)^{d+\alpha-1}} \cdot \frac{\tau^\delta}{(\tau^{1/\alpha} + |z - x|)^{d+\alpha-1}} dz \\ & \leq C \frac{\alpha}{1 + \alpha\delta} \left(1 + \delta B\left(\frac{1}{\alpha}, \delta\right) \right) \frac{t^{\delta+1/\alpha}}{(t^{1/\alpha} + |y - x|)^{d+\alpha-1}}, \end{aligned}$$

valid for $\delta > -1/\alpha$, where $C > 0$, and $B(\cdot, \cdot)$ is the Euler beta function. We obtain for $k \geq 1$

$$|V_k(t, x, y)| \leq \frac{(2N)^{k+1} (C\|a\|)^k}{\alpha} \frac{1}{k!} \frac{t^{k/\alpha}}{(t^{1/\alpha} + |y - x|)^{d+\alpha-1}} \prod_{n=1}^{k-1} \left(1 + \frac{n}{\alpha} B\left(\frac{1}{\alpha}, \frac{n}{\alpha}\right) \right).$$

Note, that $r_k = \frac{(2NC\|a\|t^{1/\alpha})^k}{k!} \prod_{n=1}^{k-1} \left(1 + \frac{n}{\alpha} B\left(\frac{1}{\alpha}, \frac{n}{\alpha}\right) \right)$ is positive and the relation

$$\lim_{k \rightarrow \infty} \frac{r_{k+1}}{r_k} = \lim_{k \rightarrow \infty} \frac{2NC\|a\|t^{1/\alpha}}{k+1} \left(1 + \frac{k}{\alpha} B\left(\frac{1}{\alpha}, \frac{k}{\alpha}\right) \right) = 0$$

is true. Therefore, the series on the right hand side of (10) converges uniformly in $x \in \mathbb{R}^d$, $y \in \mathbb{R}^d$ and locally uniformly in $t > 0$. Thus, the function V , given by the equality (10), is a solution of the equation (9). In addition, the following inequality

$$|V(t, x, y)| \leq C_T \frac{1}{(t^{1/\alpha} + |y - x|)^{d+\alpha-1}} \quad (12)$$

is proved for $x \in \mathbb{R}^d$, $y \in \mathbb{R}^d$ and $0 < t \leq T$, where C_T is a positive constant that may be depended on $T > 0$.

Remark. The constructed function $V(t, x, y)$ is the unique solution of equation (9) in the class of functions that satisfy inequality (12).

Define the function $G(t, x, y)$ by the equality (8) where the function $V(t, x, y)$ is defined in (10). Then we can perform the following calculations

$$\begin{aligned} (\mathbf{B}_x G(t, x, y), e(x)) &= V_0(t, x, y) + \int_0^t d\tau \int_{\mathbb{R}^d} V_0(t - \tau, x, z) V(\tau, z, y) |a(z)| dz \\ &= V(t, x, y). \end{aligned}$$

We here took the possibility of applying of the operator \mathbf{B} under integral, which is proved in the following Lemma.

Lemma. The equality

$$\mathbf{B}_x \int_0^t d\tau \int_{\mathbb{R}^d} g(t - \tau, x, z) V(\tau, z, y) |a(z)| dz = \int_0^t d\tau \int_{\mathbb{R}^d} \mathbf{B}_x g(t - \tau, x, z) V(\tau, z, y) |a(z)| dz$$

is true.

Proof. Let us consider a set of operators $\{\mathbf{B}^\varepsilon : \varepsilon > 0\}$ that act on a continuously differentiable bounded function $(\varphi(x))_{x \in \mathbb{R}^d}$ according to the following rule

$$(\mathbf{B}^\varepsilon \varphi)(x) = \frac{2c}{\alpha \varkappa} \int_{|u| \geq \varepsilon} \frac{\varphi(x + u) - \varphi(x)}{|u|^{d+\alpha}} y dy.$$

It is clear that $\lim_{\varepsilon \rightarrow 0+} (\mathbf{B}^\varepsilon \varphi)(x) = (\mathbf{B}\varphi)(x)$ for all functions φ , described above, and $x \in \mathbb{R}^d$.

The inequalities (11) and (12) allow us to assert that

$$\begin{aligned} & \left| \frac{u}{|u|^{d+\alpha}} (g(t - \tau, x + u, z) - g(t - \tau, x, z)) V(\tau, z, y) |a(z)| \right| \\ & \leq \frac{const}{|u|^{d+\alpha-1}} \left(\frac{t - \tau}{((t - \tau)^{1/\alpha} + |z - x - u|)^{d+\alpha}} + \frac{t - \tau}{((t - \tau)^{1/\alpha} + |z - x|)^{d+\alpha}} \right) \\ & \times \frac{1}{(\tau^{1/\alpha} + |y - z|)^{d+\alpha-1}}. \end{aligned}$$

It is easy to see that the right hand side of this inequality is the integrable function with respect to (u, τ, z) on the set $\{|u| \geq \varepsilon\} \times (0; t) \times \mathbb{R}^d$ for all $t > 0$ and $x \in \mathbb{R}^d, y \in \mathbb{R}^d$. Here we used the results of [2, Lemma 5], where it is proved that

$$\begin{aligned} & \int_0^t d\tau \int_{\mathbb{R}^d} \frac{(t - \tau)^{\beta/\alpha}}{((t - \tau)^{1/\alpha} + |z - x|)^{d+\alpha+k}} \frac{\tau^{\gamma/\alpha}}{(\tau^{1/\alpha} + |y - z|)^{d+\alpha+l}} dz \\ & \leq C \left[B \left(\frac{\beta - k}{\alpha}, 1 + \frac{\gamma}{\alpha} \right) t^{\frac{\beta+\gamma-k}{\alpha}} \frac{1}{(t^{1/\alpha} + |y - x|)^{d+\alpha+l}} \right. \\ & \left. + B \left(1 + \frac{\beta}{\alpha}, \frac{\gamma - l}{\alpha} \right) t^{\frac{\beta+\gamma-l}{\alpha}} \frac{1}{(t^{1/\alpha} + |y - x|)^{d+\alpha+k}} \right] \end{aligned} \quad (13)$$

for $-\alpha < k < \beta, -\alpha < l < \gamma$ and $C > 0$, which depends only on d, α, k and l .

Therefore, we obtain the following equality

$$\mathbf{B}_x^\varepsilon \int_0^t d\tau \int_{\mathbb{R}^d} g(t - \tau, x, z) V(\tau, z, y) |a(z)| dz = \int_0^t d\tau \int_{\mathbb{R}^d} \mathbf{B}_x^\varepsilon g(t - \tau, x, z) V(\tau, z, y) |a(z)| dz, \quad (14)$$

using the Fubini theorem.

The inequalities (12), (13) and $|\mathbf{B}_x g(t, x, y)| \leq \frac{\text{const}}{(t^{1/\alpha} + |y - x|)^{d+\alpha-1}}$ allow us to assert that the integral $\int_0^t d\tau \int_{\mathbb{R}^d} \mathbf{B}_x g(t - \tau, x, z) V(\tau, z, y) |a(z)| dz$ exists. Now we have to pass to the limit with $\varepsilon \rightarrow 0+$ in the equality (14) to complete the proof of Lemma. \square

We have thus got that the function $G(t, x, y)$ is the perturbation of the transition probability density $g(t, x, y)$ of a symmetric stable process.

Considering estimates (12), (11) and inequality (13), we can write for $t \in (0; T]$, $x \in \mathbb{R}^d$, $y \in \mathbb{R}^d$

$$\begin{aligned} |G(t, x, y)| &\leq N \frac{t}{(t^{1/\alpha} + |y - x|)^{d+\alpha}} \\ &+ NC_T \|a\| \int_0^t d\tau \int_{\mathbb{R}^d} \frac{t - \tau}{((t - \tau)^{1/\alpha} + |z - x|)^{d+\alpha}} \frac{1}{(\tau^{1/\alpha} + |y - z|)^{d+\alpha-1}} dz \\ &\leq \frac{Kt}{(t^{1/\alpha} + |y - x|)^{d+\alpha-1}} \left(1 + \frac{1 + t^{1/\alpha}}{t^{1/\alpha} + |y - x|} \right), \end{aligned}$$

where K is a positive constant, which depends on T , α , c , $\|a\|$ and d . Note that the right hand side of the last inequality can be estimated from above by the following expression

$$\frac{\hat{K}t^{1-1/\alpha}}{(t^{1/\alpha} + |y - x|)^{d+\alpha-1}} \leq \hat{K}t^{-d/\alpha},$$

where $\hat{K} = (2T^{1/\alpha} + 1)K$.

2 THE FUNDAMENTAL SOLUTION OF THE CAUCHY PROBLEM

It is known (see [2]) that the function $g(t, x, y)$ is the fundamental solution of the Cauchy problem (3) and, in addition, the function

$$u(t, x) = \int_{\mathbb{R}^d} \varphi(y) g(t, x, y) dy + \int_0^t d\tau \int_{\mathbb{R}^d} g(t - \tau, x, y) f(\tau, y) dy$$

is the solution of the Cauchy problem

$$\begin{aligned} \frac{\partial u(t, x)}{\partial t} &= \mathbf{A}_x u(t, x) + f(t, x), \quad t > 0, x \in \mathbb{R}^d, \\ u(0+, x) &= \varphi(x), \quad x \in \mathbb{R}^d, \end{aligned} \tag{15}$$

for any bounded continuous functions $(\varphi(x))_{x \in \mathbb{R}^d}$ and $(f(t, x))_{t > 0, x \in \mathbb{R}^d}$. Moreover, this solution is unique in the class of functions that vanish as $|x| \rightarrow \infty$.

Thus, the function

$$\begin{aligned} U(t, x) &= \int_{\mathbb{R}^d} \varphi(y) G(t, x, y) dy \\ &= \int_{\mathbb{R}^d} \varphi(y) g(t, x, y) dy + \int_0^t d\tau \int_{\mathbb{R}^d} g(t - \tau, x, y) \int_{\mathbb{R}^d} V(\tau, y, z) \varphi(z) dz |a(y)| dy \end{aligned}$$

is the unique (in the class of functions that tends to zero at infinity) solution of the Cauchy problem (15) with $f(t, x) = \int_{\mathbb{R}^d} V(t, x, z) \varphi(z) dz |a(x)|$.

Now we note that $V(t, x, y) = (\mathbf{B}_x G(t, x, y), e(x))$. Then

$$f(t, x) = \int_{\mathbb{R}^d} (\mathbf{B}_x G(t, x, z), a(x)) \varphi(z) dz = (a(x), \mathbf{B}_x U(t, x)),$$

and the function $U(t, x)$ is a solution of the Cauchy problem for the equation (4) with bounded continuous function $a(x)$ and operators \mathbf{A} and \mathbf{B} defined by equalities (1) and (5) respectively.

Let us prove that the function $G(t, x, y)$ satisfies the equation of Kolmogorov-Chapman

$$G(t + s, x, y) = \int_{\mathbb{R}^d} G(s, x, z) G(t, z, y) dz \quad (16)$$

for all $s > 0, t > 0, x \in \mathbb{R}^d, y \in \mathbb{R}^d$. Note, the function $g(t, x, y)$ satisfies the equation (16).

Let $(\varphi(x))_{x \in \mathbb{R}^d}$ be a continuous bounded function. Put $U(s, x, \varphi) = \int_{\mathbb{R}^d} G(s, x, y) \varphi(y) dy$, $u(s, x, \varphi) = \int_{\mathbb{R}^d} g(s, x, y) \varphi(y) dy$ and $W(s, x, \varphi) = \int_{\mathbb{R}^d} V(s, x, y) \varphi(y) dy$.

Note, that the function $W(t, x, \varphi)$ is the unique solution of the following equation

$$W(t, x, \varphi) = W_0(t, x, \varphi) + \int_0^t d\tau \int_{\mathbb{R}^d} V_0(t - \tau, x, z) W(\tau, z, \varphi) |a(z)| dz, \quad (17)$$

where $W_0(s, x, \varphi) = \int_{\mathbb{R}^d} V_0(s, x, y) \varphi(y) dy$.

Then the function $U(s, x, \varphi)$ can be given by the equality (see (5))

$$U(t, x, \varphi) = u(t, x, \varphi) + \int_0^t d\tau \int_{\mathbb{R}^d} g(t - \tau, x, z) W(\tau, z, \varphi) |a(z)| dz.$$

Now, let us find the function $U(t + s, x, \varphi)$. We have

$$\begin{aligned} U(t + s, x, \varphi) &= u(t + s, x, \varphi) + \int_0^{t+s} d\tau \int_{\mathbb{R}^d} g(t + s - \tau, x, z) W(\tau, z, \varphi) |a(z)| dz \\ &= \int_{\mathbb{R}^d} g(s, x, y) u(t, y, \varphi) dy \\ &\quad + \int_{\mathbb{R}^d} g(s, x, y) dy \int_0^t d\tau \int_{\mathbb{R}^d} g(t - \tau, y, z) W(\tau, z, \varphi) |a(z)| dz \\ &\quad + \int_t^{s+t} d\tau \int_{\mathbb{R}^d} g(t + s - \tau, x, z) W(\tau, z, \varphi) |a(z)| dz \\ &= \int_{\mathbb{R}^d} g(s, x, y) U(t, y, \varphi) dy \\ &\quad + \int_0^s d\tau \int_{\mathbb{R}^d} g(s - \tau, x, z) W(t + \tau, z, \varphi) |a(z)| dz. \end{aligned}$$

Therefore, the function $W_t(s, x, \varphi) = W(t + s, x, \varphi)$ satisfies the equation (17), where the function φ is replaced by $U(t, \cdot, \varphi)$. Then $W(t + s, x, \varphi) = W(s, x, U(t, \cdot, \varphi))$ and we arrive at the equality $U(t + s, x, \varphi) = U(s, x, U(t, \cdot, \varphi))$ or, what is the same,

$$\begin{aligned} \int_{\mathbb{R}^d} G(t + s, x, y) \varphi(y) dy &= \int_{\mathbb{R}^d} G(s, x, z) \int_{\mathbb{R}^d} G(t, z, y) \varphi(y) dy dz \\ &= \int_{\mathbb{R}^d} \varphi(y) dy \int_{\mathbb{R}^d} G(s, x, z) G(t, z, y) dz. \end{aligned}$$

Then the relation (16) is proved because the function φ is an arbitrary bounded continuous one.

Next, we get $\int_{\mathbb{R}^d} G(t, x, y) dy = 1$ from (8) and (9), because there are obvious equalities

$$\int_{\mathbb{R}^d} g(t, x, y) dy = 1 \quad \text{and} \quad \int_{\mathbb{R}^d} V_0(t, x, y) dy = \left(\mathbf{B}_x \int_{\mathbb{R}^d} g(t, x, y) dy, e(x) \right) = 0$$

for all $t > 0, x \in \mathbb{R}^d$, and the uniqueness of the solution of equation (9) leads us to the identity $\int_{\mathbb{R}^d} V(t, x, y) dy \equiv 0$.

Unfortunately, we can not guarantee non-negativity of the function $G(t, x, y)$ and the existence of a Markov process with the generating operator $\mathbf{A} + (a(\cdot), \mathbf{B})$.

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З допомогою методу теорії збурень знайдено фундаментальний розв'язок деякого класу псевдо-диференціальних рівнянь. Розглянуто симетричний α -стійкий процес в багатовимірному евклідовому просторі. Його генератор \mathbf{A} є псевдо-диференціальним оператором чий символ задається функцією $-c|\lambda|^\alpha$, де $\alpha \in (1, 2)$ і $c > 0$ задані стали. Векторнозначний оператор \mathbf{B} має символ $2ic|\lambda|^{\alpha-2}\lambda$. Побудовано фундаментальний розв'язок рівняння $u_t = (\mathbf{A} + (a(\cdot), \mathbf{B}))u$ з неперервною обмеженою векторнозначною функцією a .

Ключові слова і фрази: стійкий процес, задача Коші, псевдо-диференціальне рівняння, щільність ймовірності переходу.